

# INF280: Competitive programming

Advanced datastructure algorithms

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# Dynamic programming

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# What is Dynamic Programming (DP)?

## Hard to define but roughly:

- we have a question depending on parameters
- that can be answered recursively
- the subproblems might appear multiple times or overlap

We don't really care what is *officially* a dynamic programming problem...

# What is Dynamic Programming (DP)?

## Alternative definition:

- we have a state (the parameters)
- we have transitions (the recursion)
- we compute a function over the states using the transitions

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⇒ a graph problem! (usually acyclic graph)

## Some typical DP problems

Compute  $F_n$  the  $n$ -th Fibonacci number

- **question(parameter):** compute  $\text{fibo}(n)$
- **recursion:**  $F_n = F_{n-1} + F_{n-2}$
- **overlapping subproblems:**

$$F_{n+2} = F_{n+1} + F_n = (F_n + F_{n-1}) + F_n$$

# Some typical DP problems

I have weights  $w_1 \dots w_k$  can I reach a weight of  $T$

- **question(parameter):**  $\text{reach}(w_1, \dots, w_k, T)$
- **recursion:**  $\text{reach}(w_1, \dots, w_k, T) = \text{reach}(w_2, \dots, w_k, T) \vee \text{reach}(w_2, \dots, w_k, T - w_1)$
- **overlapping subproblems:**  
if, e.g.,  $w_1 = 1, w_2 = 2, w_3 = 3$  we can achieve  $T = 3$  in two different ways

## Memoization

Memoization consists of storing the result of a function, so different calls with the same parameters can be answered directly.

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## DP vs Memoization

Typical DP solutions use memoization but DP can be seen as something much larger...



## DP vs Greedy algorithms

Both DP and Greedy algorithms can be applied to problems with a large set of configurations to be explored.

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DP approach generally explores the full set of configurations by breaking down large problems into smaller problems while avoiding to compute twice the same thing

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## **Greedy algorithms**

A greedy approach makes locally optimal choices leading to a globally optimal solution.

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## Dynamic Programming

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## Greedy algorithms

A greedy approach makes locally optimal choices leading to a globally optimal solution. Some algorithms are said greedy even if they lead to non optimal solutions

**Let us solve some simple DP  
problems!**

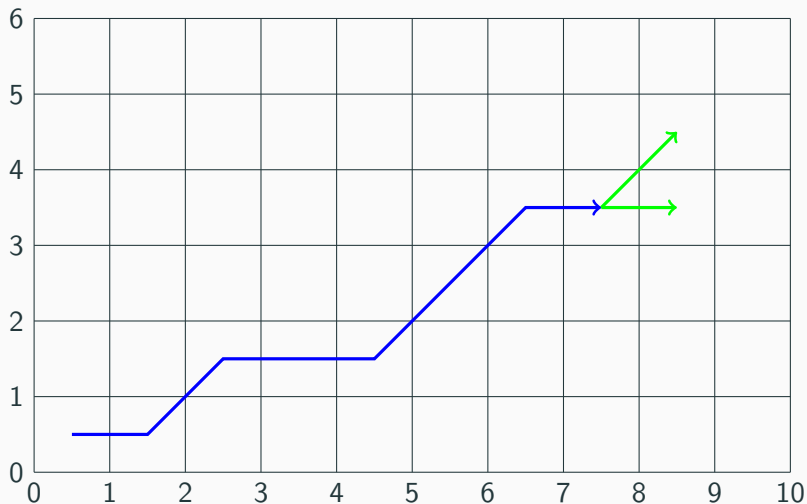
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## Exercise 1 to 4

## **Classical types of DP problems**

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## Path on grids



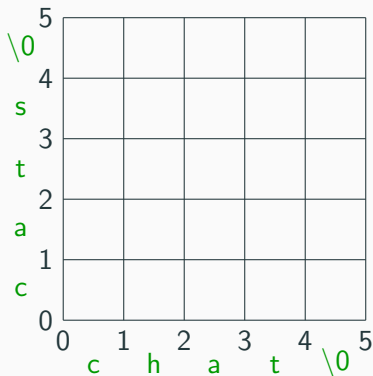
**Applications:** Number of down-right paths, Levenshtein distance



# Levenshtein distance

## Levenshtein distance

Given two words  $u_1 \dots u_\ell$ ,  $v_1 \dots v_k$  what is the number of edits (replace, delete, or insert letter) needed to transform  $u$  into  $v$ ?



$$\text{dist}(i, j) = \min$$

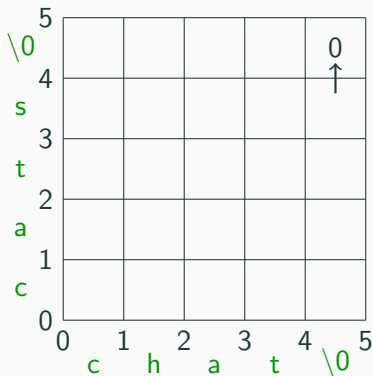
- $\text{dist}(i, j + 1) + 1$ ,
- $\text{dist}(i + 1, j) + 1$ ,
- $\text{dist}(i + 1, j + 1) + 1$ ,
- $\text{dist}(i + 1, j + 1)$  si  $v_i = u_j$

$\Rightarrow O(n^2)$  solution!

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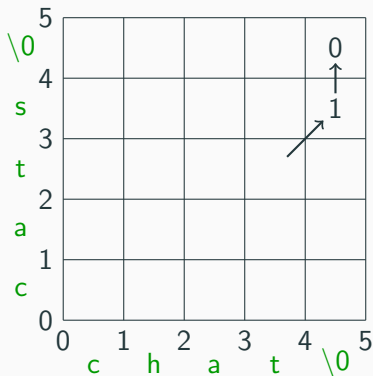


- insert s

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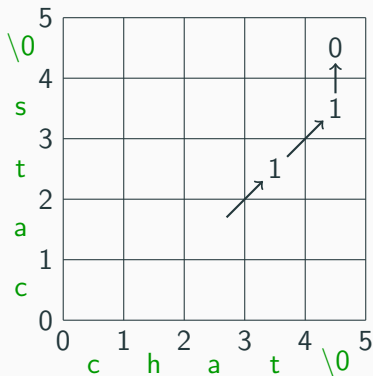


- insert s
- t=t

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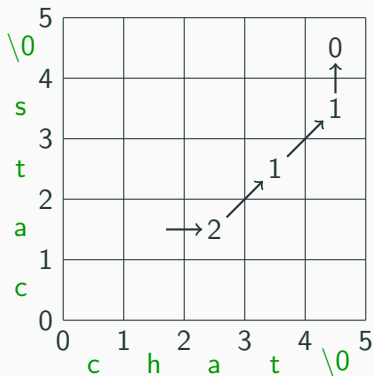


- insert s
- t=t
- a=a

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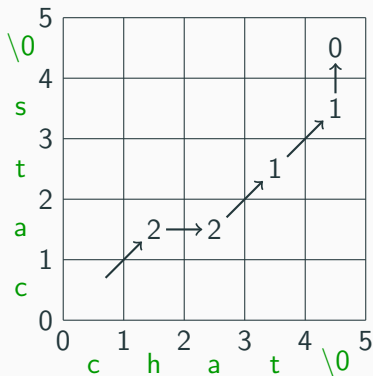


- insert s
- t=t
- a=a
- delete h

# Levenshtein distance

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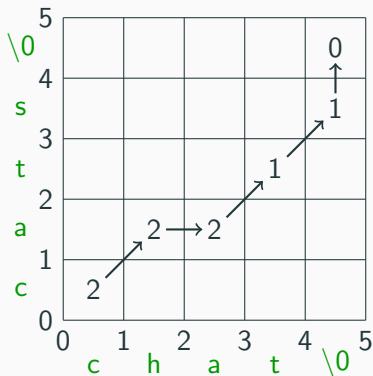


- insert s
- t=t
- a=a
- delete h
- c=c

# Levenshtein distance

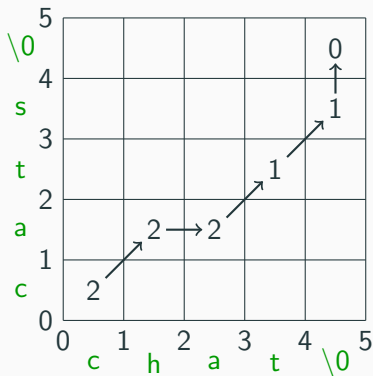
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- insert s
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# Levenshtein distance



## Alternative solution

- we have a graph
- we can run a shortest path algorithm!

$\Rightarrow$  in  $O(n \times d)$  where  $d$  is the distance.



**Fix any ordering and then:**

$\text{subsets}(e_1, \dots, e_n) = \text{subsets}(e_2, \dots, e_n)$  with or without  $e_1$

**Some considerations:**

- the target function needs to be “composable”
- sometimes the order matters
- using bitmasks might help

## Range DP problem

Given an array  $A$  compute some metric on all subarrays  $A[i : j]$ .

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- in the simple case  $do(i, j) \rightarrow \forall_{i < k < j} do(i, k) \wedge do(k, j) \quad O(n^3)$
- sometimes  $do(i, j) = do(i + 1, j) \wedge do(i, j - 1) \quad O(n^2)$
- sometimes you need to have a clever trick to compute the full solution...

Generally memory is not an issue with DP but you might have very few possible values over a large possible universe.

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Use sets and hashsets!

## **Special cases of DP**

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# Implementing a DP requires an acyclic recursion

## What to do when the recursion might be cyclic?

- not care about it
  - enforce it with a new parameter
  - changing the problem
- 

## Examples

- use a DFS (DFS can be seen as DP with cyclicity)
- use a shortest path
- use the DAG of strongly connected components
- use an ad-hoc solution

**How to improve an inefficient DP  
solution?**

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## Write the recursive decision problem and

- **for each parameter:**
  - what are the possible values (min/max/nb)?
  - can it be deduced from the other parameters?
  - is it a strict equality?
- **for the recursion formula:**
  - can it be simplified?
  - are we recomputing the same thing twice?
  - can we precompute some part of it?
  - can we use an approach different from memoization?



## How to implement DP solutions?

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# The problem and its solution

## Levenshtein

we have two words  $u_1 \dots u_\ell$  and  $v_1 \dots v_k$  what is the edit distance between them?

## Recursive solution

- $dist(i, j) =$  distance between  $u_0 \dots u_i$  and  $v_0 \dots v_j$

## Levenshtein

we have two words  $u_1 \dots u_\ell$  and  $v_1 \dots v_k$  what is the edit distance between them?

## Recursive solution

- $dist(i, j)$  = distance between  $u_0 \dots u_i$  and  $v_0 \dots v_j$
- $dist(-1, -1) = i + j + 2$  when  $i < 0$  or  $j < 0$
- $dist(i, j) = dist(i - 1, j - i)$  when  $u_i = v_j$
- $dist(i, j) = 1 + \min(dist(i - 1, j), dist(i, j - 1), dist(i - 1, j - 1))$

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## Constructive solution

$dist(i, j) =$  distance between  $u_0 \dots u_{i-1}$  and  $v_0 \dots v_{j-1}$ .  $dist(i, j)$  is the biggest number such that:

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- we have  $dist(0, 0) = 0$
- $dist(i + 1, j + 1) = dist(i, j)$  when  $u_i = v_j$
- $dist(i + 1, j) \leq 1 + dist(i, j)$
- $dist(i, j + 1) \leq 1 + dist(i, j)$
- $dist(i + 1, j + 1) \leq 1 + dist(i, j)$

# The recursive approach

```
const char u[Tm], v[Tm] ;
int dyn[Tm][Tm] ; // initialized to -INF
int dist( int i , int j ) {
    if(i<0 || j<0) // can only be -1 if negative
        return i+j+2; // avoid out of bounds access
        // i+j+2 = size of the non-empty string
    int & cur = dyn[i][j] ;
    if ( cur == -INF ) {
        if(u[i] == v[j])
            cur = dist(i-1,j-1);
        else
            cur = 1 + min(dist(i-1,j-1), dist(i-1,j), dist(i,j-1)) ;
    }
    return cur ;
}
```

## The iterative approach

```
const char u[Tm], v[Tm] ;
int dist[Tm][Tm]; // dist[i][j]= dist(u_0..u_{i-1}, v_0..v_{j-1})
void min_equal(int & a, int b) { if(a>b) a=b;}
void compute_dist() {
    fill(dist[0], dist[Tm], INF) ;
    dist[0][0] = 0;
    for(int i = 0 ; u[i] ; i++)
        for(int j = 0 ; v[j] ; j++) {
            // at step (i,j) we set the value dist[i][j]
            if(i > 0) min_equal(dist[i][j],1+dist[i-1][j]);
            if(j > 0) min_equal(dist[i][j],1+dist[i][j-1]);
            if(i > 0 && j>0 )
                if(u[i-1] == v[j-1]) min_equal(dist[i][j], dist[i-1][j-1]);
                else min_equal(dist[i][j], 1+dist[i-1][j-1]);
        } // answer in dist[lengthU-1][lengthV-1]
}
```

## The iterative approach (alternative)

```
const char u[Tm], v[Tm] ;
int dist[Tm][Tm] ;

void compute_dist() {
    fill(dist[0], dist[Tm], INF) ;
    dist[0][0] = 0;
    for(int i = 0 ; u[i] ; i++)
        for(int j = 0 ; v[j] ; j++) {
            // at step (i,j) we ``propagate'' the value dist[i][j]
            if(u[i] == v[j]) min_egal(dist[i+1][j+1], dist[i][j]);
            min_egal(dist[i+1][j+1], 1+dist[i][j]);
            min_egal(dist[i+1][j], dist[i][j]);
            min_egal(dist[i][j+1], dist[i][j]);
        }
} // answer in dist[lengthU][lengthV]
```